

Renesas USB MCU

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USB Peripheral Human Interface Devices Class Driver Using Firmware Integration Technology Modules

Introduction

This document describes the following sample firmware: USB Peripheral Human Interface Devices Class Driver for using Firmware Integration Technology. The sample firmware is referred to below as the PHID. During actual software development, make sure to refer to the USB Peripheral Human Interface Devices Class Driver f using Firmware Integration Technology application note (document No. R01AN2663EJ) in combination with the USB Basic Host and Peripheral Driver using Firmware Integration Technology application note (document No. R01AN2025EJ) and the user's manual (hardware) of the microcontroller used.

Target Device

RX63N/RX631 Group
RX64M Group
RX71M Group

The operation of this program has been confirmed using the Renesas Starter Kit (RSK).

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1. Introduction

1.1 Functions

The PHID conforms to the USB human interface device (HID) class specification and implements communication with HID devices.

The PHID provides the following functionalities:

1. Operation as a Full-Speed (12 Mbps) device.
2. It is recognized as an HID device when connected to a USB host, and transfers data as a virtual mouse or virtual keyboard.

1.2 FIT Module Configuration

The PHID comprises the following FIT modules and a sample application:

Table 1-1 FIT Module Configuration

FIT Module	Folder Name	Version
Board Support Package Module Using Firmware Integration Technology	r_bsp	2.81
Renesas USB MCU USB Basic Host and Peripheral firmware Firmware Integration Technology	r_usb_basic	1.11
Renesas USB MCU USB Peripheral Human Interface Devices Class Driver(HID) Firmware Integration Technology	r_usb_phid	1.11

Refer to the related documentation for details of each FIT module. Note that the latest versions of the FIT modules used by the sample firmware are available for download from the following website:

Renesas Electronics website: <http://www.renesas.com/>

1.3 Operating Confirmation Environment

The environment required for the PHID to operate is described below:

1) Evaluation Board

Renesas Starter Kit+ for RX63N (RSK+RX63N): Product No: R0K50563NC000
RX63N Group Renesas Microcontroller Development Starter Kit from Renesas Electronics

Renesas Starter Kit+ for RX64M (RSK+RX64M): Product No: R0K50564MC010BR
RX64M Group Renesas Microcontroller Development Starter Kit from Renesas Electronics

Renesas Starter Kit+ for RX71M (RSK+RX71M): Product No: R0K5RX71MC010BR
RX71M Group Renesas Microcontroller Development Starter Kit from Renesas Electronics

2) Development Environment

- a) e²studio integrated development environment, from Renesas Electronics
- b) RX Family C/C++ compiler package, version 2.03.00, from Renesas Electronics
- c) E1 or E20 emulator from Renesas Electronics

3) Other

- a) HID Host (PC: Microsoft Windows® 7, Windows® 8, Windows® 8.1, or Windows® 10)
- b) Host PC for emulator (Microsoft Windows® 7, Windows® 8, or Windows® 8.1)
- c) USB cable
- d) User cable (packaged with E1 or E20 emulator)
- e) Emulator cable (packaged with E1 or E20 emulator)

1.4 Setup

1.4.1 Hardware

Figure 1-1 shows an example operating environment for the PHID. Refer to the associated instruction manuals for details on setting up the evaluation board and using the emulator, etc.

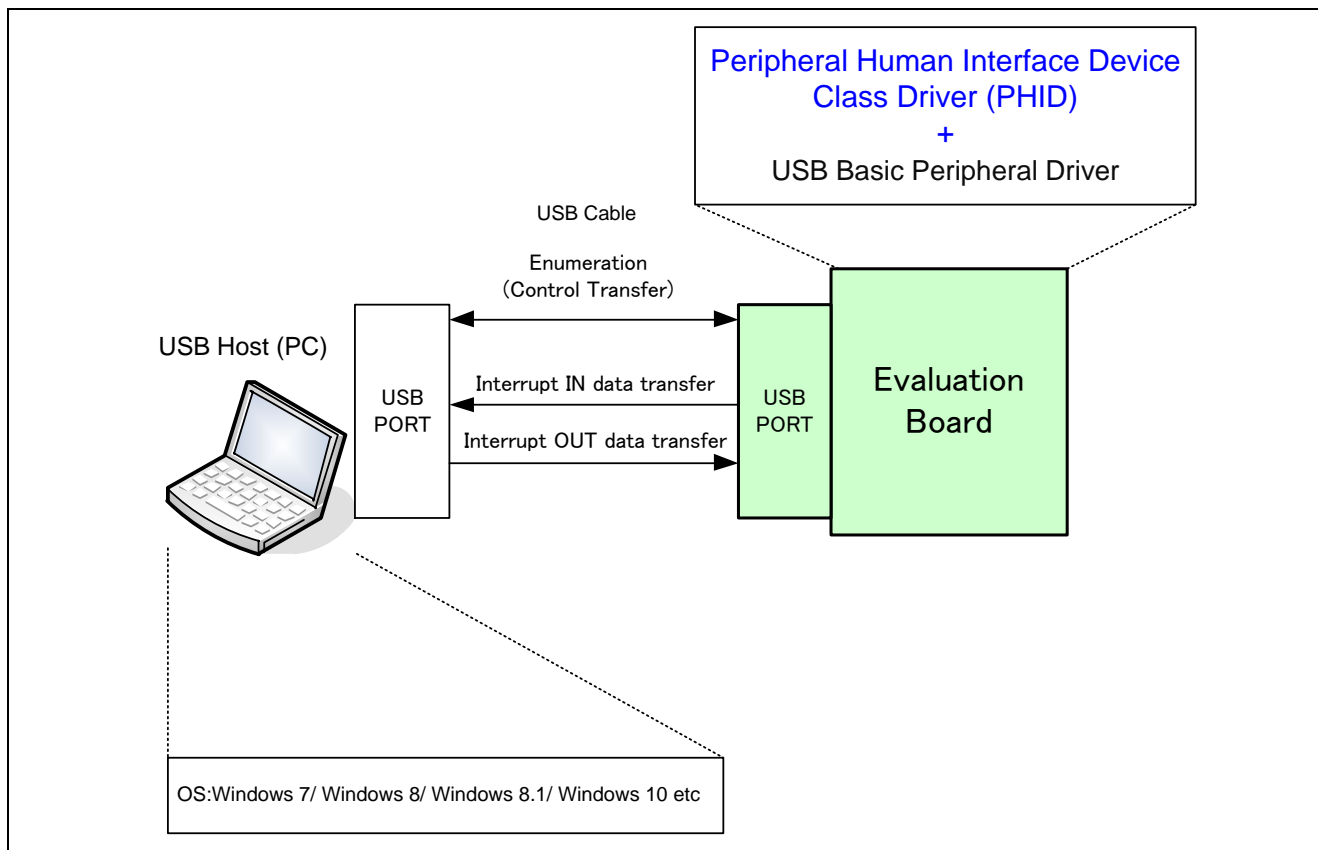


Figure 1-1 Example Operating Environment

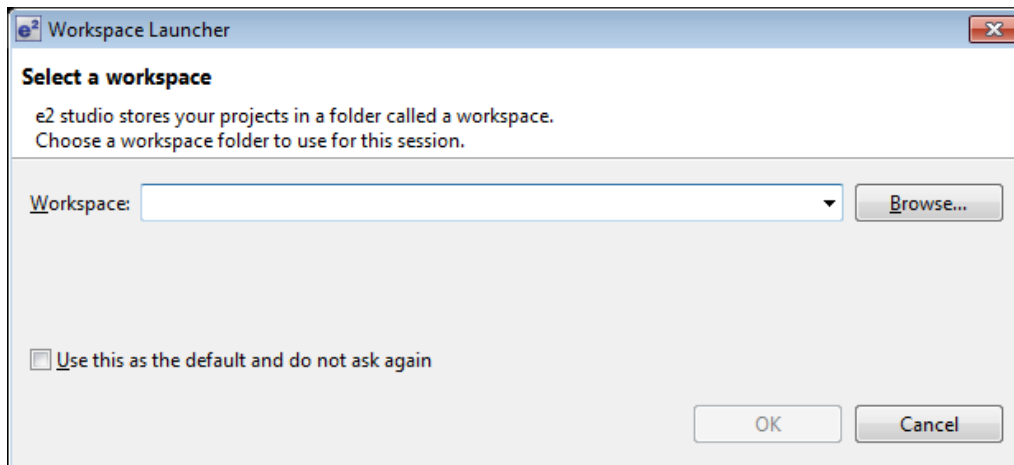
Table 1-2 shows the evaluation board on which operation has been confirmed.

Table 1-2 Evaluation Board on which PHID operation has been verified

MCU	Evaluation Board
RX63N	RSK+RX63N
RX64M	RSK+RX64M
RX71M	RSK+RX71M

1.4.2 Software

- 1) Setup e² studio
 - a) Start e² studio
 - b) If you start up e² studio at first, the following dialog is displayed. Specify the folder to store the project in this dialog.



- c) Click Workbench icon

Welcome to e²studio



Overview

Get an overview of the features



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First Steps

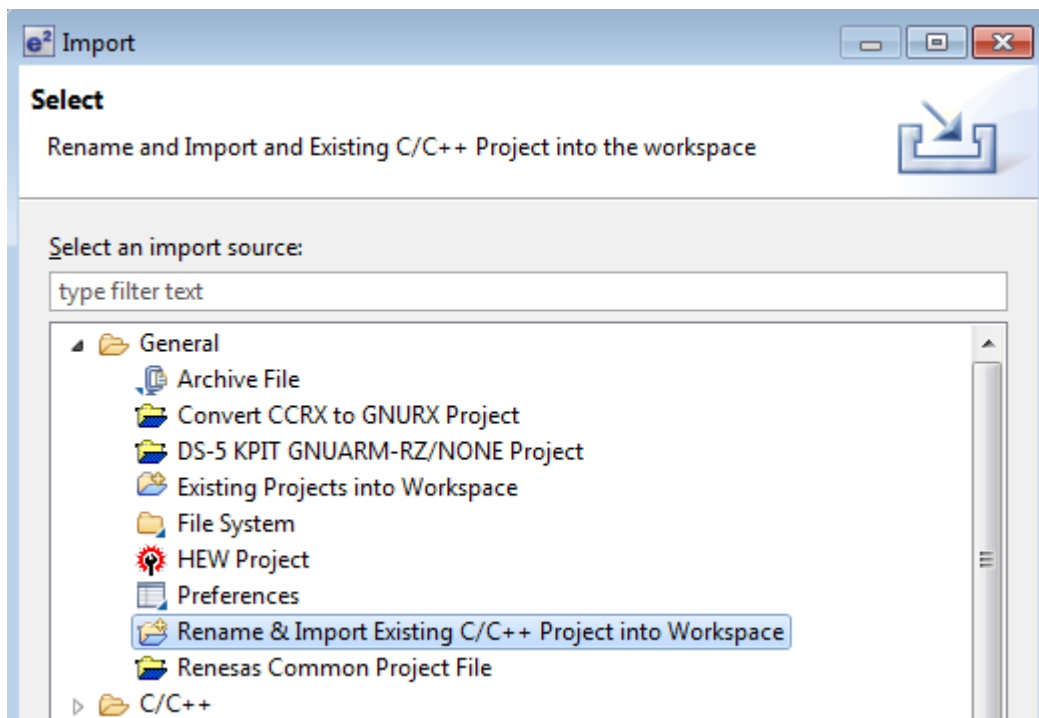
Take your first steps



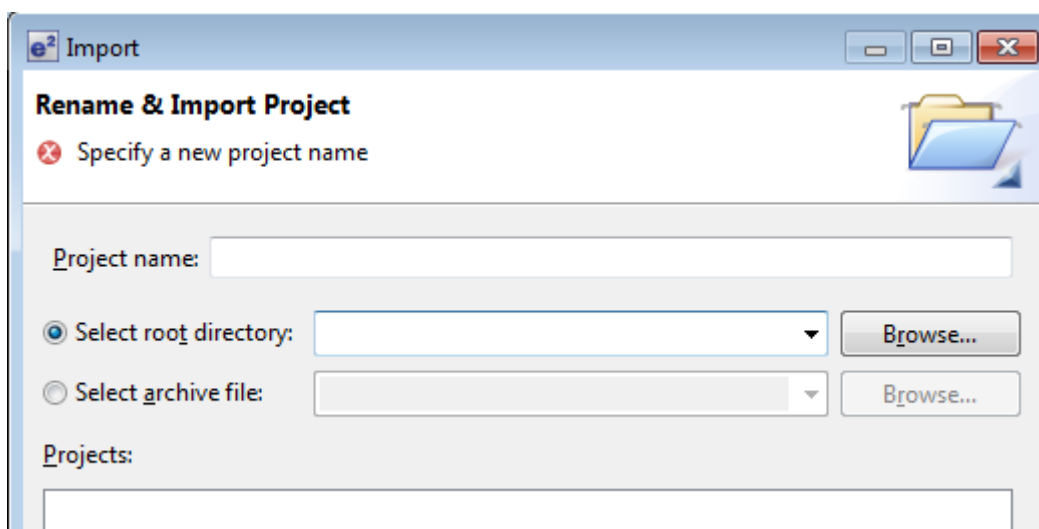
Workbench

Go to the e2 studio workbench

- 2) Import the project to the workspace
 - a) Select [File] > [Import]
 - b) Select “General => Rename & Import Existing C/C++ Project into Workspace”



Select the root directory of the project, that is, the folder containing the “.cproject” file.



- c) Click “Finish”.

You have now imported the project into the workspace. Note that you can import other projects into the same workspace.
- 3) Generate the binary target program by clicking the “Build” button.
- 4) Connect the target board to the debug tool and download the executable. The target is run by clicking the “Run” button.

2. Software Configuration

2.1 Module Configuration

The PHID comprises a HID class driver as well as mouse and keyboard device drivers. In response to data transfer requests from the APL, it transfers data to the USB host, via the PCD.

Figure 2-1 shows the module configuration of the PHID, and Table 2-1 lists the functions of the modules.

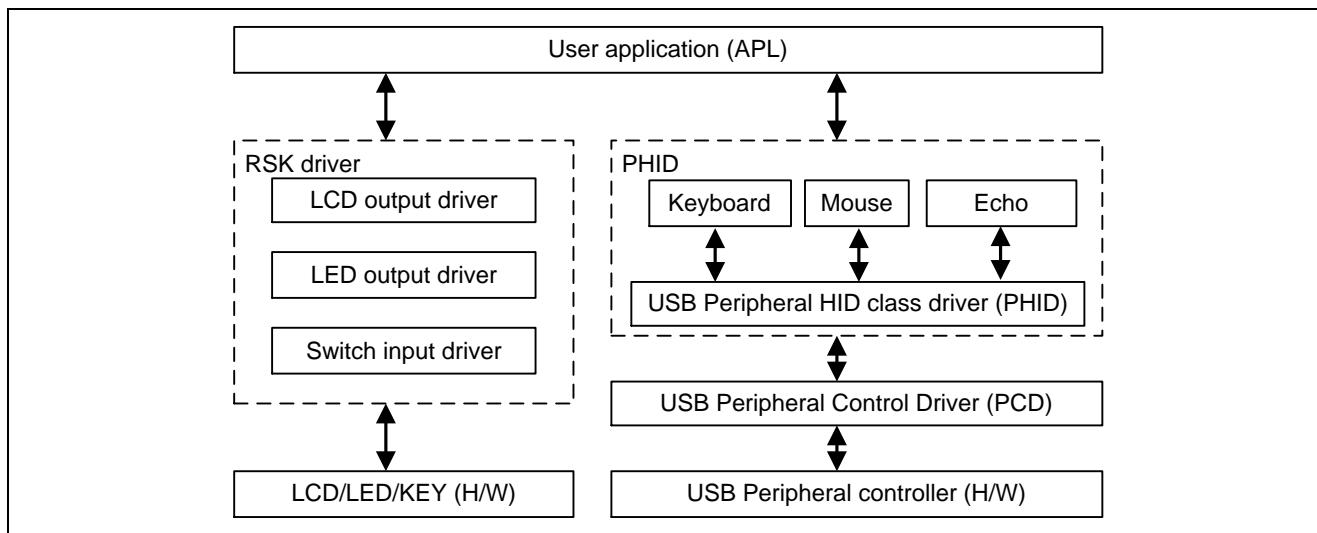


Figure 2-1 Module Configuration

Table 2-1 Function of Moudles

Module Name	Function
APL	Sample application program
RSK driver	Sample application for using the peripheral functions on the RSK board.
PHID (r_usb_phidi)	Interprets requests from the HID host. Reports APL key operation information to the HID host, via the PCD.
PCD (r_usb_basic)	USB Peripheral Hardware Control Driver

3. Sample Application

3.1 Application Specifications

The main functionalities of the PHID sample application (APL) are described below.

(1). Keyboard Mode: Keyboard Functionality

When the RSK connects to the USB host, the USB host recognizes the RSK as a keyboard. The RSK operates as a keyboard, transmitting keyboard data to the USB host using interrupt IN transfer.

(2). Mouse Mode: Mouse Functionality

When the RSK connects to the USB host, the USB host recognizes the RSK as a mouse. The RSK operates as a mouse, transmitting mouse data to the USB host using interrupt IN transfer.

(3). Echo Mode: USB Loopback Functionality (Interrupt IN/OUT Data Transfer)

The RSK connects to the USB host and performs interrupt IN/OUT data transfer. This functionality performs processing to transmit the data received from the USB host back to the USB host unaltered.

(4). Low-Power-Consumption Functionality

This functionality transitions the microcontroller to a low-power mode according to the USB state. To enable this functionality, set the macro definition `USB_CPU_LPW_PP` to `USB_LPWR_USE_PP` in the file `r_usb_basic_config.h`.

- a) In the USB suspend state, the microcontroller transitions to sleep mode.
- b) In the USB detached state, the microcontroller transitions to software standby mode.

[Note]

1. Make the selection of keyboard mode, mouse mode, or other mode in `r_usb_phid_config.h`. For details, see the application note “USB Peripheral Human Interface Device Class Driver for USB Firmware Firmware Integration Technology” (document No. R01AN2663EJ).
2. Echo mode enables communication with USB hosts supporting USB loopback functionality. Keyboard mode and mouse mode enable USB communication with PCs (USB hosts) supporting OSes such as Windows 7, Windows 8, Windows 8.1 and Windows 10.

3.2 Overview of Application Processing

The APL consists of two parts: processing of initial settings and the main loop. These are described in outline below.

3.2.1 Initial setting

The initial settings include microcontroller pin settings, USB driver settings, and USB controller initial settings.

3.2.2 Main loop (Mouse mode)

In Mouse mode the main loop performs the following processing:

- a) When enumeration with the USB host finishes, the USB driver calls the function *hid_open*, which is specified by member *devconfig* of structure *USB_PCDREG_t*. The function *hid_open* sets *EVENT_CONFIGURED* as the event value.
- b) The processing of *EVENT_USB_WRITE_START* calls the function *R_usb_phid_send_data* to request transmission of mouse data by the USB driver. When transmission of the mouse data finishes, the callback function *hid_write_trans_cb*, specified by the 4th argument of the function *R_usb_phid_send_data*, is called. This callback function sets *EVENT_USB_WRITE_COMPLETE* as the event value.
- c) The processing of *EVENT_USB_WRITE_COMPLETE* sets the transmission status variable to “not transmitting.”
- d) The processing of *EVENT_SUSPEND* calls the function *hid_low_power_control* to transition the HID device (RSK) to the low-power mode (sleep mode). Note that if the HID device (RSK) is in the suspend state, it is woken from the suspend state when a resume signal transmitted by the USB host is detected.
- e) The processing of *EVENT_NONE* captures key input information. When SW1 is pressed:
 - i. If the HID device is in the suspend state, a RemoteWakeUp signal is sent to the USB host by means of the *R_usb_phid_ChangeDeviceState* function.
 - ii. If the HID device is in the configured state, processing to set the key data (mouse data) is performed and the event value is set to *EVENT_USB_WRITE_START* in order to transmit the specified data to the USB host. The transmission status variable is set to “transmitting.”
- f) If the USB host transmits a suspend signal to the HID device (RSK) while steps b) to e) above are being processed repeatedly, the USB driver calls the function *hid_suspend* specified by member *devsuspend* in structure *USB_PCDREG_t*. The function *hid_suspend* sets *EVENT_SUSPEND* as the event value.
- g) The processing of *EVENT_SUSPEND* calls the function *hid_low_power_control* to transition the HID device (RSK) to the low-power mode (sleep mode). Note that if the HID device (RSK) is in the suspend state, it is woken from the suspend state when a resume signal transmitted by the USB host is detected.
- h) If the HID device (RSK) is detached from the USB host while steps b) to e) above are being processed repeatedly, the USB driver calls the function *hid_close* specified by member *devdetach* in structure *USB_PCDREG_t*. The function *hid_close* sets *EVENT_DETACH* as the event value.
- i) The processing of *EVENT_DETACH* calls the function *R_usb_phid_TransferEnd* to transition the HID device (RSK) to the low-power mode (software standby mode) after the data transfer request ends. If the HID device (RSK) is attached to the USB host again, enumeration starts with the USB host and the processing resumes from step a) above.

An outline of the processing of the APL is shown below.

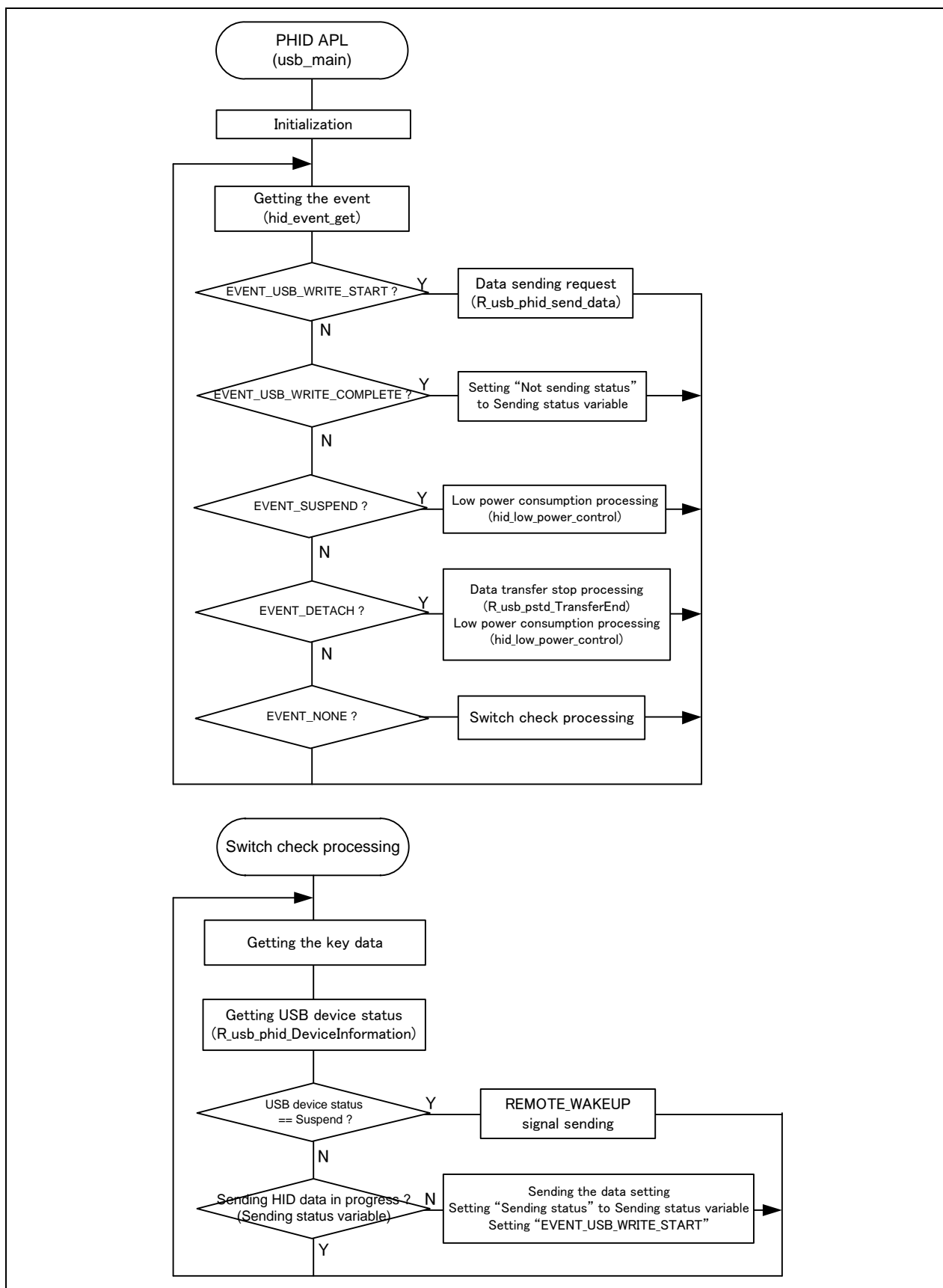


Figure 3-1 Main Loop Processing (Mouse mode)

3.2.3 Main loop (Keyboard mode)

In keyboard mode the main loop performs the following processing:

- a) When enumeration with the USB host finishes, the USB driver calls the function *hid_open*, which is specified by member *devconfig* of structure *USB_PCDREG_t*. The function *hid_open* sets *EVENT_CONFIGURED* as the event value.
- b) The processing of *EVENT_CONFIGURED* calls the function *R_usb_phid_receive_data* to request reception by the USB driver of OUT data transmitted by the USB host. When reception of the OUT data finishes, the callback function *hid_read_trans_cb*, specified by the 4th argument of the function *R_usb_phid_receive_data*, is called. This callback function sets *EVENT_USB_READ_COMPLETE* as the event value.
- c) The processing of *EVENT_USB_READ_COMPLETE* performs LED display processing based on the received OUT data, etc. It also sets *EVENT_USB_READ_START* as the event value.
- d) The processing of *EVENT_USB_WRITE_START* calls the function *R_usb_phid_send_data* to request data transfer by the USB driver of the key input data, etc., to the USB host. When transmission of the key input data, etc., finishes, the callback function *hid_write_trans_cb*, specified by the 4th argument of the function *R_usb_phid_send_data*, is called. This callback function sets *EVENT_USB_WRITE_COMPLETE* as the event value.
- e) The processing of *EVENT_USB_WRITE_COMPLETE*:
 - i. When transmission of the key input data is finished, it is necessary to transmit data consisting of 8 bytes of zeroes to the USB host to notify it of key release. Processing is performed to set the necessary zero data and the transmission status variable is set to “zero data transmission.” Also, *EVENT_USB_WRITE_START* is set as the event value.
 - ii. When transmission of the zero data is finished, the transmission status variable is set to “not transmitting.”
- f) The processing of *EVENT_NONE* determines whether or not key input has occurred. If the HID device is in the suspend state and SW1 is pressed and then released, a RemoteWakeUp signal is sent to the USB host by means of the *R_usb_phid_ChangeDeviceState* function. If a key other than SW1 is pressed, processing to set the key data takes place and the transmission status variable is set to “transmitting key data.” Also, *EVENT_USB_WRITE_START* is set as the event value in order to transmit the specified key data to the USB host.
- g) If the USB host transmits a suspend signal to the HID device (RSK) while steps b) to f) above are being processed repeatedly, the USB driver calls the function *hid_suspend* specified by member *devsuspend* in structure *USB_PCDREG_t*. The function *hid_suspend* sets *EVENT_SUSPEND* as the event value.
- h) The processing of *EVENT_SUSPEND* calls the function *hid_low_power_control* to transition the HID device (RSK) to the low-power mode (sleep mode). Note that if the HID device (RSK) is in the suspend state, it is woken from the suspend state when a resume signal transmitted by the USB host is detected.
- i) If the HID device (RSK) is detached from the USB host while steps b) to f) above are being processed repeatedly, the USB driver calls the function *hid_close* specified by member *devdetach* in structure *USB_PCDREG_t*. The function *hid_close* sets *EVENT_DETACH* as the event value.
- j) The processing of *EVENT_DETACH* calls the function *R_usb_phid_TransferEnd* to transition the HID device (RSK) to the low-power mode (software standby mode) after the data receive request ends. If the HID device (RSK) is attached to the USB host again, enumeration starts with the USB host and the processing resumes from step a) above.

An outline of the processing of the APL is shown below.

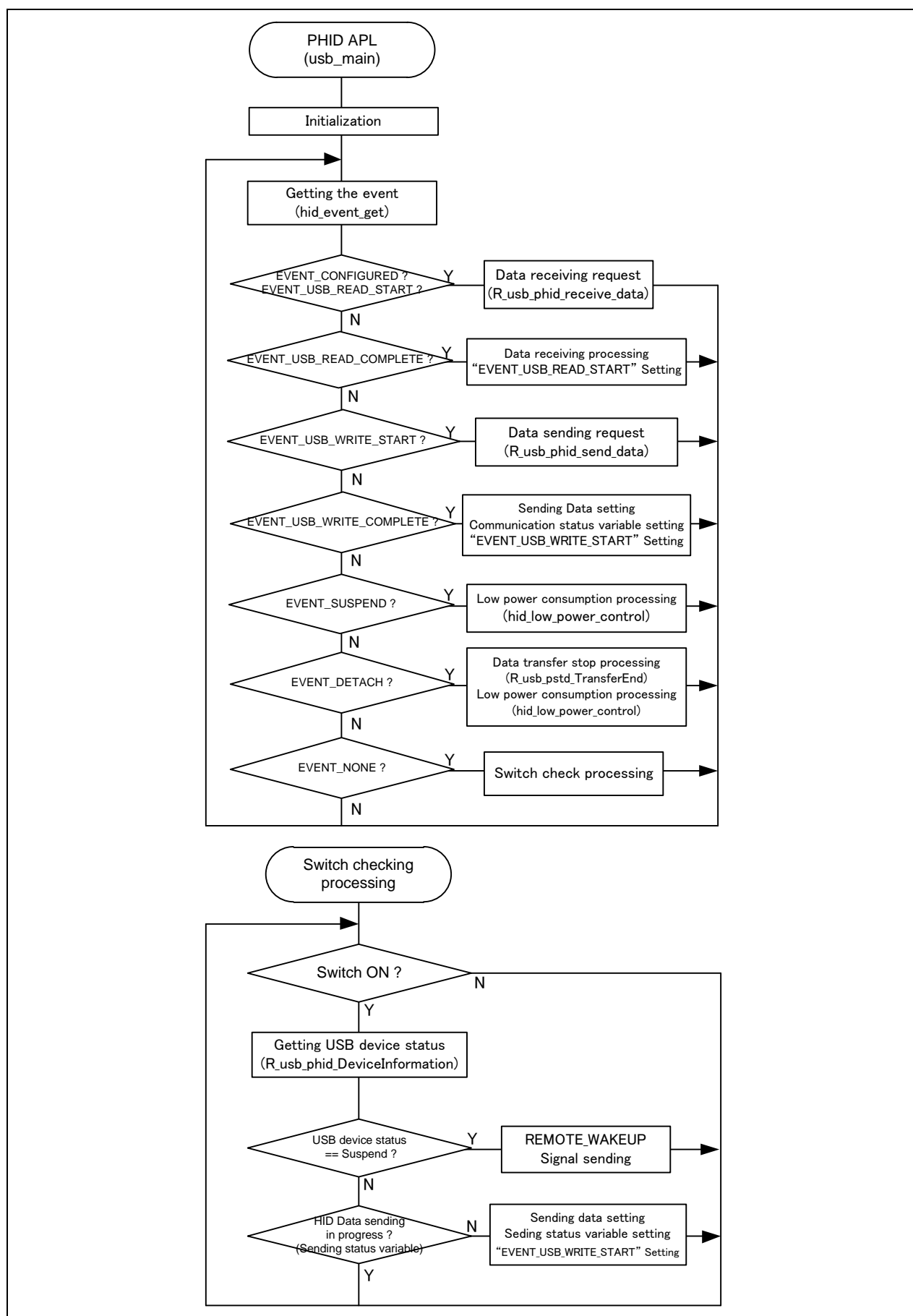


Figure 3-2 Main Loop Processing (Keyboard mode)

3.2.4 Main loop (Echo mode)

In echo mode the main loop performs the following processing:

- a) When enumeration with the USB host finishes, the USB driver calls the function *hid_open*, which is specified by member *devconfig* of structure *USB_PCDREG_t*. The function *hid_open* sets *EVENT_CONFIGURED* as the event value.
- b) The processing of *EVENT_CONFIGURED* calls the function *R_usb_phid_receive_data* to request reception of data from the USB host. When reception of the data finishes, the callback function *hid_read_trans_cb*, specified by the 4th argument of the function *R_usb_phid_receive_data*, is called. This callback function sets *EVENT_USB_READ_COMPLETE* as the event value.
- c) The processing of *EVENT_USB_READ_COMPLETE* calls the function *R_usb_phid_send_data* to transmit to the USB host the data received in b) above. When reception of the data finishes, the callback function *hid_write_trans_cb*, specified by the 4th argument of the function *R_usb_phid_send_data*, is called. This callback function sets *EVENT_USB_WRITE_COMPLETE* as the event value.
- d) The processing of *EVENT_USB_WRITE_COMPLETE* sets *EVENT_USB_READ_START* as the event value.
- e) If the USB host transmits a suspend signal to the HID device (RSK) while steps b) to d) above are being processed repeatedly, the USB driver calls the function *hid_suspend* specified by member *devsuspend* in structure *USB_PCDREG_t*. The function *hid_suspend* sets *EVENT_SUSPEND* as the event value.
- f) The processing of *EVENT_SUSPEND* calls the function *hid_low_power_control* to transition the HID device (RSK) to the low-power mode (sleep mode). Note that if the HID device (RSK) is in the suspend state, it is woken from the suspend state when a resume signal transmitted by the USB host is detected.
- g) If the HID device (RSK) is detached from the USB host while steps b) to d) above are being processed repeatedly, the USB driver calls the function *hid_close* specified by member *devdetach* in structure *USB_PCDREG_t*. The function *hid_close* sets *EVENT_DETACH* as the event value.
- h) The processing of *EVENT_DETACH* calls the function *R_usb_phid_TransferEnd* to transition the HID device (RSK) to the low-power mode (software standby mode) after the data transfer/receive request ends. If the HID device (RSK) is attached to the USB host again, enumeration starts with the USB host and the processing resumes from step a) above.

An outline of the processing of the APL is shown below.

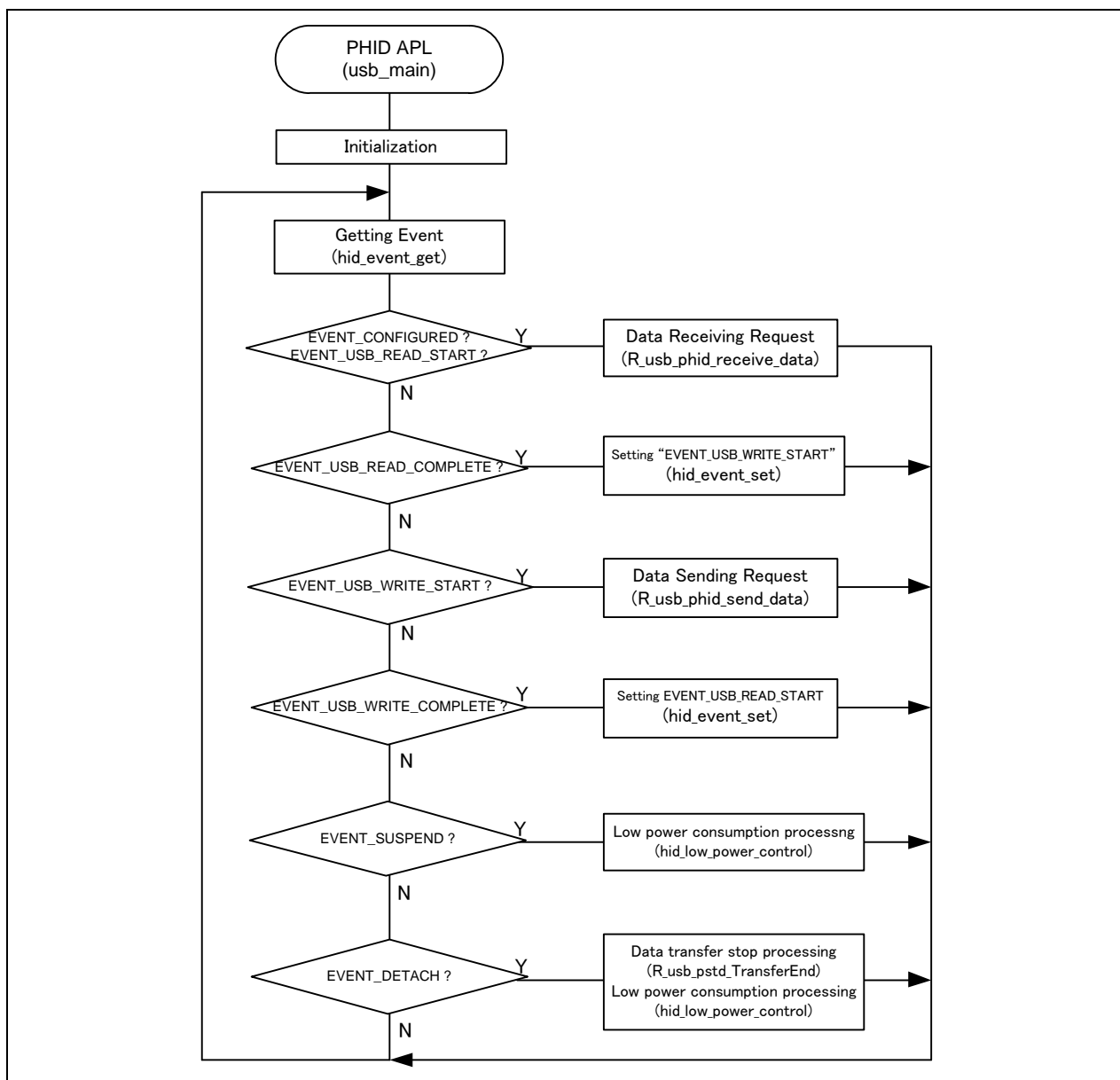


Figure 3-3 Main Loop Processing (Echo mode)

Table 3-1 Event List

Event	Description
EVENT_CONFIGURD	USB device connecting completion
EVENT_USB_READ_START	Data reception request
EVENT_USB_READ_COMPLETE	Data reception completion
EVENT_USB_WRITE_START	Data transmission request
EVENT_USB_WRITE_COMPLETE	Data transmission completion
EVENT_SUSPEND	Suspend
EVENT_DETACH	USB detach
EVENT_NONE	No event

[Note]

1. If the processing to get the event determines that the event to be fetched is not present, the event is set to "EVENT_NONE."
2. The following events are set by the callback function. The following shows the callback functions set each event

Table 3-2 Event and Callback Function

Event	Callback Function
EVENT_CONFIGURD	hid_open
EVENT_USB_READ_COMPLETE	hid_read_trans_cb
EVENT_USB_WRITE_COMPLETE	hid_write_trans_cb
EVENT_SUSPEND	hid_suspend
EVENT_DETACH	hid_close

3.2.5 Event Management

Members (event_cnt, event[]) of the following structure are used to manage states and events. This structure is prepared by the APL.

```
typedef struct DEV_INFO /* Structure for HID device control */
{
    uint16_t event_cnt; /* Event count */
    uint16_t event[EVENT_MAX]; /* Event. */
} DEV_INFO_t;
```

3.2.6 MCU Low power consumption processing

MCU low power consumption processing transitions the MCU to low-power mode when the following conditions are met:

Table 3-3 Conditions for Transition to Low-Power Mode

Transition Condition		Transition Status
VBUS	USB State	
OFF	—	Software standby mode
ON	Suspend Configured	Sleep mode
ON	Other than Suspend Configured	Normal mode (program running)

- a) When the device is detached (VBUSOFF), the APL transitions the MCU to software standby mode. Note that recovery from software standby mode occurs when the RSK board attaches to the USB host, causing a transition to normal mode.
- b) When the HID device is suspended, the APL transitions the MCU to sleep mode. Note that recovery from sleep mode occurs when a Resume signal is transmitted by the USB host, causing a transition to normal mode.

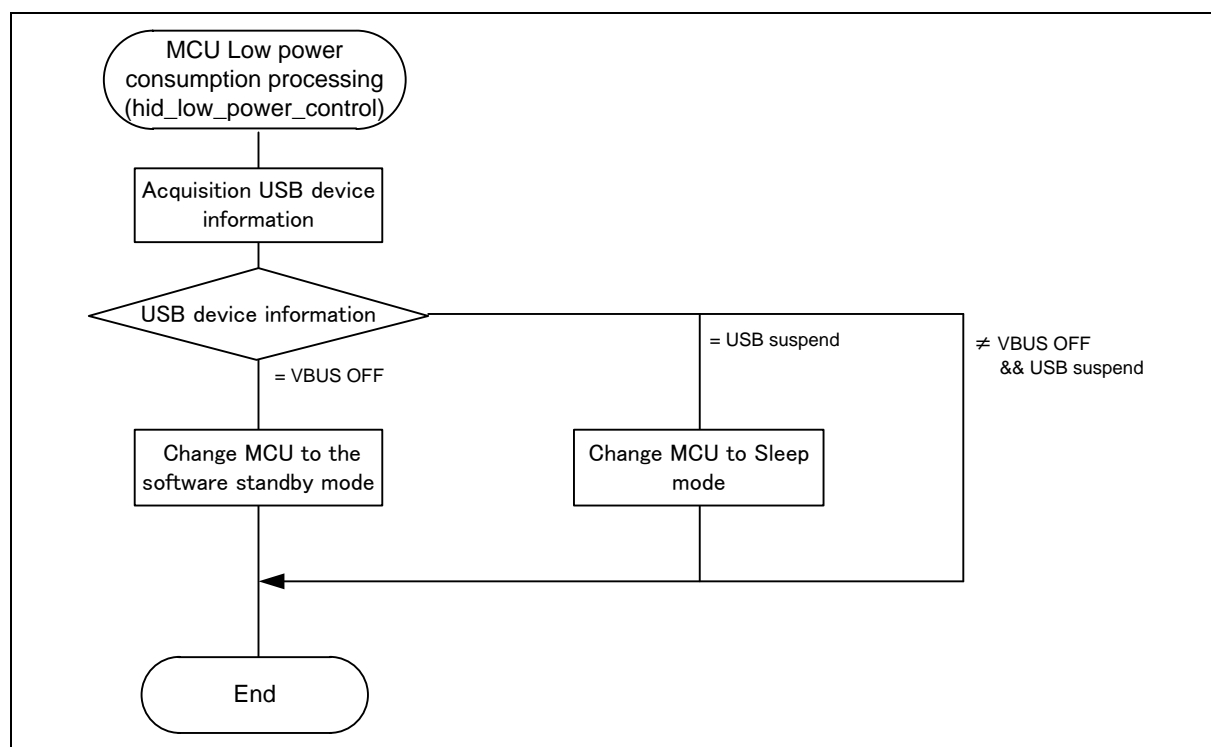


Figure 3-4 Flowchart of MCU Low Power Consumption Processing

3.3 Switch

3.3.1 Switch specification

The specifications of the switches used in mouse mode and keyboard mode are listed below. The switches on the RSK are not used in echo mode.

Note that the application program does not recognize a switch press as having occurred when the switch is only pressed down. The combination of a switch press and release is recognized as a switch press.

1) Mouse mode

Switch Number	Operation
Switch1(SW1)	Left click
Switch2(SW2)	Reports motion data for mouse up/down direction.
Switch3(SW3)	Reports motion data for mouse right/left direction.

2) Keyboard mode

Switch Number	Operation
Switch2(SW2)	One of the key codes for characters "a" to "z" or "Enter" is reported to the host each time SW is pressed.
Switch3(SW3)	One of the key codes for "1" to "9" and "0" or "Enter" is notified to the host each time SW is pressed.

(Note1) Movement data is generated when a switch is pressed and held, and the data is reported to the host. Data reporting stops when the switch is released. Pressing the switch again switches the movement direction, and movement data reporting continues.

(Note2) When switches 2 and 3 are both unpressed, in keyboard mode NULL data is transferred to the USB host, and in mouse mode no data is transferred to the USB host.

3.3.2 Data Format

The table below shows the transmit report format used for sending data to and from USB Host. These data formats are set in conjunction with the HID report descriptor contents notified to USB Host.

Table 3-4 Data Formats Used when Notifying the Host

offset	Mouse Mode (3Bytes)	Keyboard Mode (8Bytes)
0	b0 : Button 1 b1 : Button 2 b2 : Reserved	Modifier keys
1	X displacement	Reserved
2	Y displacement	Keycode 1
3		Keycode 2
4		Keycode 3
5		Keycode 4
6		Keycode 5
7		Keycode 6

Table 3-5 Keyboard OUTPUT Report format

offset (byte)	Value
0	b0 : LED 0 (NumLock) b1 : LED 1 (CapsLock) b2 : LED 2 (ScrollLock) b3 : LED 3 (Compose) 0: OFF, 1: ON

3.4 Descriptor

The PHID's descriptor information is contained in `r_usb_phid_descriptor.c`. Also, please be sure to use your vendor ID.

4. Class Request

Table 4-1 shows the class requests supported by PHID.

Table 4-1 Supported Basic Requests and HID Class Requests

Request	Code	Description	Supported
Get Report	0x01	Sends a report to the USB Host	YES
Set Report	0x09	Receives a report from the USB Host	YES
Get Idle	0x02	Sends a duration (time) to the USB Host	YES
Set Idle	0x0A	Receives a duration (time) from the USB Host	YES
Get Protocol	0x03	Sends a protocol to the USB Host	NO
Set Protocol	0x0B	Receives a protocol from the USB Host	NO
Get Report Descriptor	Standard	Sends a report descriptor to the USB Host	YES
Get HID Descriptor	Standard	Sends an HID descriptor to the USB Host	YES

5. Using the e² studio project with CS+

The PHID contains a project only for e² studio. When you use the PHID with CS+, import the project to CS+ by following procedures.

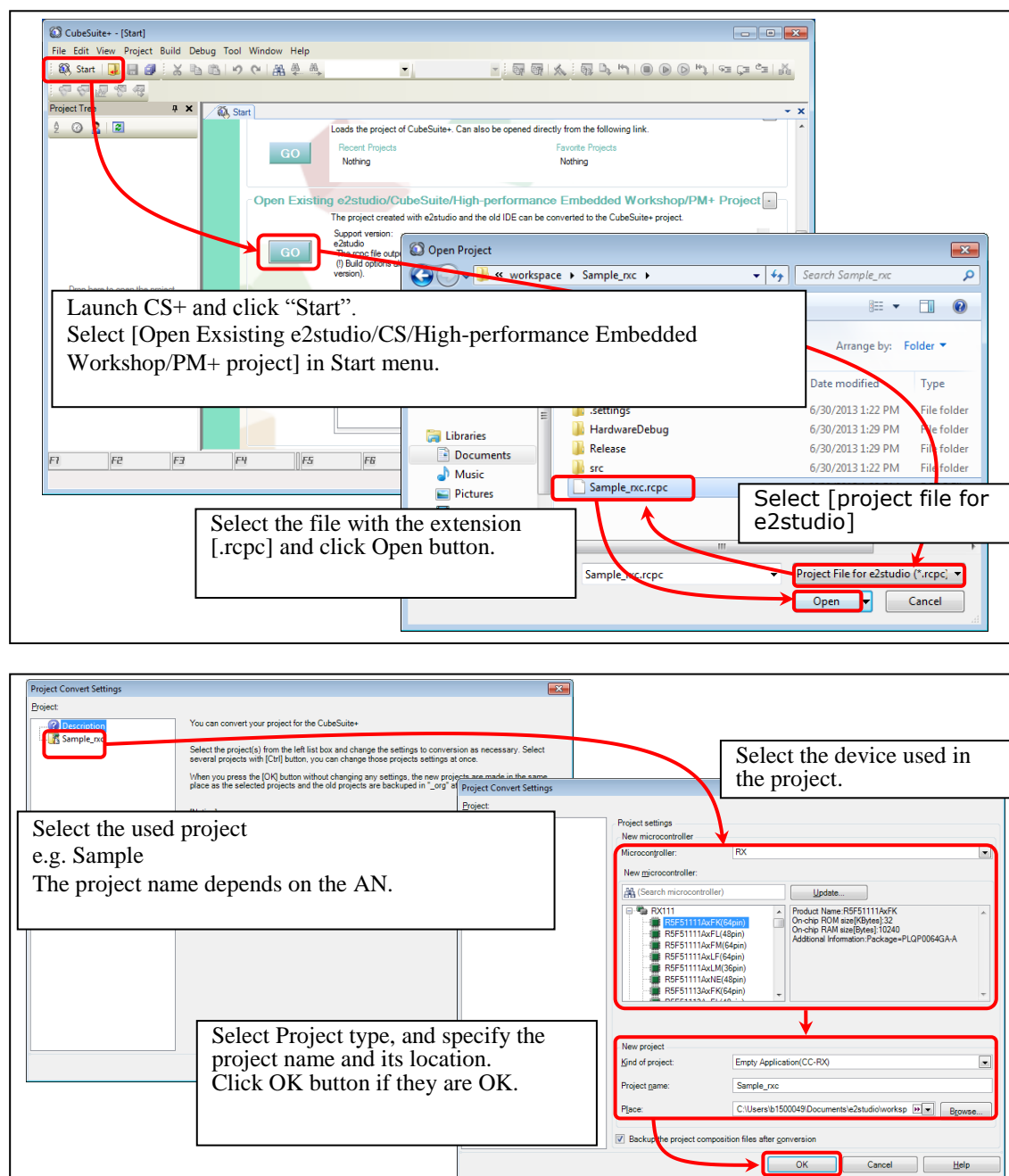


Figure 5-1 Using the e² studio project with CS+

Website and Support

Renesas Electronics Website

<http://www.renesas.com/>

Inquiries

<http://www.renesas.com/inquiry/>

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Revision Record

Rev.	Date	Description	
		Page	Summary
1.11	Sep 30, 2015	—	First Edition Issued.

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

- The characteristics of an MPU or MCU in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
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